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(54) Title: AUTOMATIC CONTROL USING PROXIMITY SENSORS			
(57) Abstract Proximity sensors e.g. for use on lift doors. The systems shown has a number of improved features including bootstrapping the receptor antennae to avoid capacitance problems, arranging an antenna as pairs of antenna strips with circuitry to enable the location of a signal source relative to the antenna to be determined such that the antenna has asymmetric sensitivity, and circuitry to detect the presence of undersized potential trigger signals from door wobble, etc. and hence reduce the sensitivity to avoid such false triggers.			

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AUTOMATIC CONTROL USING PROXIMITY SENSORS.

This invention relates to automatic control using proximity sensors, e.g. for controlling doors and the like. Its principal application is in the control of lift doors, though it may be used in various analogous applications, e.g. machine safety guards, vehicle reversing aids and the like.

For many years lift doors have been controlled by electromechanical apparatus. There has been a very substantial amount of effort directed to door control while nevertheless avoiding inconvenience to users of the lift. Many such systems rely on proximity sensors to detect the presence of a person or object which obstructs the door or would obstruct it. The problem with many such systems is that they work electronically and find difficulty in distinguishing between people and, for example, metal parts of the lift shaft construction.

PCT Patent Application No: PCT/GB 82/00022, Publication No: WO 82/02536, discloses proximity detector circuitry suitable for use in connection with lift doors. The systems described therein (and described in several of the Patent Specifications cited in the search report forming part of the publication) do represent workable systems. However, they suffer from a number of disadvantages, in particular, the necessity of fairly careful installation

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and balancing procedures, which are not always easy to effect on site, and additionally they tend to require in any practical application association with one or more microswitches which operate as the door moves. Mechanical components such as microswitches are costly to install and adjust.

We have now found that by using a somewhat different alternative approach, and using circuitry which can easily be constructed compactly and robustly, it is possible to produce improved lift door control circuits which will both detect the presence of a person or object obstructing the door or about to do so and act to interrupt or prevent a door closing operation and, further, which can detect the presence of a person or object adjacent the door and initiate a door opening operation.

One problem with many standard systems concerns the design of sensor antennae which are designed to extend along the edge of a door or edges of a pair of doors, that edge or edges being the leading edge(s) when the doors are closing. There are two separate problems which arise: First it is desirable that the antenna "looks" asymmetrically relative to the door. It is important to be able to detect people coming up to a lift door from outside in order to be able to abort a closing operation and reopen the doors, but it is equally important not to prevent closing because of the close proximity of people already safely inside the lift. In the past, asymmetric deep guard channels have been used partially to surround the antenna and give an asymmetric field of sensitivity. These take up space and are tricky to install and adjust.

A second problem is that the sensitivity of the signal picked up by the antenna is effectively heavily diluted by the capacitance between antenna

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and guard. This capacitance which can be quite high e.g. of the order of 100 picofarad, needs to be compared with the alteration in capacitance between antenna and ground when a body e.g. a person  
5 approaches the antenna. The change may be several orders of magnitude less, thus giving very small changes of potential on the antenna itself. The input signal to whatever subsequent circuitry is used is effectively severely attenuated.

10 According to a first feature of the present invention there is provided proximity sensor apparatus including one or more antennae and circuitry associated with the or each antenna and designed to feed and detect a high frequency signal  
15 picked up by the antenna(e), the antenna(e) having associated with it, and located between it and ground, a further electrode, the further electrode being electrically connected to follow the voltage induced on the antenna(e).

20 Such an arrangement, conveniently called for reasons which will appear below, a bootstrap electrode, serves to mask the antenna from the normal grounded guard and accordingly to remove the capacitance dilution effect noted above. Preferably the  
25 antenna electrode and bootstrap electrode are connected together via an emitter follower.

Preferably the antenna is a strip of conductive material on one side of a printed circuit board and the bootstrap electrode is a strip of conductive  
30 material, conveniently somewhat broader than the antenna strip, on the other side of the printed circuit board.

The antenna output may be taken from the emitter of the transistor via a simple screened lead to  
35 appropriate processing circuitry. Using the printed circuit board technique of construction just noted,

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it is possible to construct very thin assemblies of antenna and bootstrap electrode which are ideally suited for installation along the leading edge of a door and which take up very little space.

5       Appropriate driver circuitry may be provided to inject e.g. a 50 kHz signal to ground, this signal then appearing on e.g. a person approaching the antenna so that it can be picked up by the antenna and processed using suitable circuitry. The  
10       International Patent Publication mentioned above gives details of such circuitry.

      If desired, sensitivity may be increased by detecting signals from the antenna only corresponding to the frequency of the signal applied to ground.  
15       This can serve to eliminate false signals due to interference e.g. from electromechanical components such as motors and relays which may be associated with the apparatus the proximity detector is designed to control. A balanced synchronous detector system  
20       of known type may be used.

      In particularly hostile environments, interference rejection may be substantially improved by using a modulated high frequency signal applied to ground and detected via the antenna, e.g. a 50 kHz signal  
25       modulated at 1 kHz.

      The improved antenna structure described above is not particularly directional. Asymmetric detection may be achieved by providing a pair of (or more than two) parallel antennae strips, each preferably provided  
30       with its own bootstrap electrode as noted above, and each being associated with appropriate comparator circuitry in order to enable signal processing to be carried out with a comparison of the signals received by the two antennae. Since for many angles of approach  
35       to the antennae, one antenna will be closer to e.g. an approaching body than the other, the signal on that

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antenna will be correspondingly greater. By subtracting the signal or a signal derived therefrom in respect of one antenna from the corresponding signal or derived signal from the other, a positive or negative signal may be produced which will give an indication of which side something is approaching from. This can be easily adapted to render detection circuitry sensitive to movement outside of a lift shaft but not inside it.

According to yet a further feature of the present invention, an antenna proximity detection system of the type indicated above is combined with an optical sensor system, e.g. one using infrared emitting diodes and standard detection circuits to give an interaction, in accordance with appropriate preset logic, between proximity detection from an antenna type detector circuit and detection arising from the interruption of an infrared light beam. Such an approach is of particular value in connection with door control where metal objects are to be regularly taken past the door. For example lifts in hospitals and industrial sites often have metal trolleys, beds or the like wheeled in and out of them. Interruption of such a beam may be arranged to desensitise the antenna based system, which would then immediately be resensitised when the beam was re-established.

Further features and advantages of the present invention will become apparent from the following description of a lift door proximity detection system, which is taken in conjunction with the accompanying drawings. In these drawings:

Figure 1 is a diagrammatic representation of an antenna, bootstrap antenna and transistor stage arrangement,  
Figure 2 is a block diagram of a synchronous detector system,

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Figure 3 is a block diagram showing the overall circuitry of a working lift door control system, and

5 Figure 4 is a diagrammatic illustration of a split antenna with appropriate circuitry to provide asymmetric sensitivity.

Referring to the drawings Figure 1 shows diagrammatically an antenna arrangement and its immediately associated circuitry. The actual antenna  
10 is constituted by a flat plate electrode 1 which may conveniently be a strip of copper foil on one side of a piece of printed circuit board. On the other side of the circuit board a similarly shaped but slightly larger piece of copper foil constitutes a so-called  
15 bootstrap electrode 2. The piece of printed circuit board on which electrodes 1 and 2 are found is mounted in a flat metal channel which constitutes an earth plane 3, the channel being mounted along e.g. the leading edge of a lift door with the antenna electrode  
20 1 facing away from the door.

Electrodes 1 and 2 are directly connected to the base and emitter respectively of a single transistor stage consisting of the transistor itself, two biasing resistors as shown and a capacitor. Any AC signal  
25 received by the electrode will be transferred via the bootstrap emitter follower to the bootstrap electrode 2, the signal on the latter being passed also to the capacitor via which an AC output signal may be extracted at 4.

30 This signal may be fed to the input 5 of the synchronous detector shown diagrammatically in Figure 2. The signal is passed to a phase splitter 6 and the resulting two signals, 180° apart, passed to analogue gates 7 and 8, which gates are fed with respective  
35 signals 180° out of phase from a suitable master oscillator which originated the original signal picked



up by the antenna 1. The outputs of the analogue gates are fed via a simple resistor capacitor network to an output terminal 9.

5 Figure 3 shows the full block diagram circuit of a lift door control system. At the left of the Figure can be seen pairs of antenna and bootstrap electrodes 1, 2, and at the right of the Figure, a power supply 24, relay circuit 40 and oscillator 22.

10 The output of the 50-100KHz oscillator within the unit 22 is connected via a flying lead 21 to the metalwork of a door assembly which carries all the detector circuitry, so that a 12v.p-p squarewave signal appears between the detector circuit assembly and external ground, i.e. any persons or conductive objects  
15 adjacent to the door.

This signal is received at the antennae 1 via stray capacitance between the antennae and earth such that under normal circumstances (no obstruction close to the door) a fairly small and equal oscillator voltage is  
20 induced at all three bootstrap amplifier inputs. The bootstrap electrode 2 behind each antenna 1 greatly increases the voltage received at the antennae by minimising the stray capacitance to detector ground. The received A.C. signal is thus fed to each of 3 synchronous  
25 detectors which are driven by oscillator 22 via a buffer and phase splitter 20, and which thus rectify the signal inputs to D.C. outputs proportional to the antenna voltages. Being synchronous with the input signal these circuits have an excellent interference rejection  
30 performance and greatly reduce the likelihood of a spurious trigger due to interference from contactors etc.

The D.C. signals are amplified by the detector circuits and at this point are of the order of one volt due to the static signal from the surroundings of the  
35 device combined with about 10-100mV fluctuations induced by the close proximity of persons entering the doorway.

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It is now necessary to divide the signal path in such a way that a static or 'courtesy hold' trigger can be generated separately from the 'dynamic' long range trigger signal. To this end, a ganged set of 3 offset  
5 circuits 30 produces output signals which are D.C. offset by an adjustable amount from the direct signal. The D.C. offset forms a threshold which is used to determine whether one of the antennas is giving considerably more signal than the others by comparing the  
10 direct and offset signals in three comparators 34, 36 and 38. Any difference greater than the offset voltage will cause an output trigger and will be permanent as long as the detector is close to the person or object inducing the signal.

15 To derive a long range dynamic sensitivity, i.e. one which can reverse the door before contact with an obstruction but which is generated by an object moving with respect to the detector, further A.C. amplification is required. This is provided by three dynamic  
20 amplifiers 42, 44 and 46, which have a time constant of approximately 0.5 seconds and a voltage gain of about 100 times.

A very small change of input is thus sufficient to cause a large but short lived negative going output swing  
25 into two combiner/selector circuits 48 and 50. Combiner/selector 48 is used to determine the most positive output of the three dynamic amplifiers whilst combiner/selector 50 selects the most negative output present.

To achieve a dynamic trigger, the output of combiner/  
30 selector 50 must fall below the voltage on the negative going input of comparator 52 which is derived from a sensitivity determining circuit consisting of components 54, 56, 58, 60 and 62 as shown.

This circuit can discriminate between an obstruction  
35 in the doorway and the approach of the door to e.g. a door frame or other symmetrical metalwork and thus reduce the

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detector sensitivity when the door is approaching signal inducing metalwork which is part of the door structure. The principle used is to combine the output of a dynamic sensitivity control 58, which sets the maximum  
5 sensitivity, with the output of a comparator 60 which is fed with the overall static signal from the upper antenna and the amplified output of the maximum selector 48. Whichever of these gives the lowest output voltage determines the threshold for comparator 52 and hence the  
10 dynamic sensitivity of the unit. As the detector approaches a door frame etc., roughly equal signals are induced in all three antennas and the 'maximum' output is close to the 'minimum' output. This causes the output of amplifier 54 to pull down the threshold on  
15 comparator 52 negative input at a greater speed than the output of 50 is falling and a trigger will not occur. In addition, if a very large static output from the upper antenna is present the comparator 60 will change state and switch off the dynamic sensitivity completely so that  
20 a fully open or closed door will only be 'static' sensitive. Vibration of the door near the frame etc. is thus unlikely to cause spurious triggers.

When a person is present in the doorway the moving detector (moving on the leading edge of the moving door)  
25 will have much greater signals on one antenna compared to the others, due to the irregular outline of the body which is approaching it and this causes the difference between the maximum and minimum selector outputs to be much greater. The threshold on comparator 52 thus  
30 remains close to that derived from 58 alone and a trigger is readily achieved to reverse the door movement.

Figure 4 shows how directional sensitivity may be achieved by the use of two parallel antennas within a channel at the edge of a door by carrying out a  
35 differential comparison of the output signals from the two antennae. In such an arrangement, the antenna closer

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to a moving object will provide the greater output and thus the direction of approach can be determined from the polarity of the differential between the signals from the two antennae. It is thus possible to cause a trigger to occur for an object approaching from outside a lift car but to ignore movement by persons already within the car. This directional sensitivity may be rotated in azimuth by varying the relative gain of the antenna amplifiers. In the practical application shown in Figure 4, two antenna strips 100, 102, each approximately 6 mm wide are located about 25 mm apart on a single printed circuit board. Associated with each antenna is a bootstrap electrode as described above. The antennae are connected via amplifiers 104 and synchronous detectors 106 to a pair of differential amplifiers 108, 110, which respectively derive a direct sum output and a differential output of adjustable gain and polarity for steering purposes. The sum output is used to drive a normal detector circuit 112 to trigger door opening if a signal above a certain threshold is present with any angle of approach, whilst the differential signal inhibits the detector circuit trigger when the person generating the signal is in the sector within the car from which it is not desired to generate a door opening signal.

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CLAIMS

1. Proximity sensor apparatus including a plurality of antennae arranged, e.g. along the edge of a lift door,  
5 means to receive and process signals picked up by the antennae and to generate a response, e.g. a lift door opening signal, on the detection of a difference in received signal between the antennae greater than a minimum threshold level, and wherein the circuitry  
10 includes means for selecting a maximum signal from among the plurality of signals received, means for selecting a minimum signal from the plurality of signals received, means for determining the difference between the maximum and minimum signals and means for increasing the threshold  
15 as the difference between the maximum and minimum signals decreases.

2. Proximity sensor apparatus including an antenna and means for processing a signal picked up by the antenna to  
20 provide a control signal, wherein the antenna includes a pair of parallel antennae strips each associated with comparator circuitry in order to enable signal processing to be carried out including a comparison of the signals received by the two antennae, means for detecting which  
25 antenna is receiving the greater signal and means for subtracting the signal or a signal derived therefrom in respect of one antenna from the corresponding signal or derived signal from the other to give a positive or negative signal indicative of the position of an object  
30 emitting a signal picked up by the antenna relative to the pair of antennae strips.

3. Proximity sensor apparatus including one or more antennae and circuitry associated with the or each antenna  
35 and designed to feed and detect a high frequency signal picked up by the antenna(e), the antenna(e) having

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associated with it, and located between it and ground, a further electrode, the further electrode being electrically connected to follow the voltage induced on the antenna(e).

5

4. Proximity sensor apparatus according to claim 3 wherein the antenna(e) include(s) at least two parallel antenna strips and circuitry connected thereto as set out in claim 2.

10

5. Proximity sensor apparatus including a plurality of antennae set in a lift door, wherein each antenna has a further electrode associated therewith as set out in claim 3, at least one of the antennae has a pair of parallel antenna strips arranged and connected as set out in claim 2, and wherein the signal processing circuitry connected to at least some of the antennae is arranged to operate as set out in claim 1.

15

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FIG. 1.

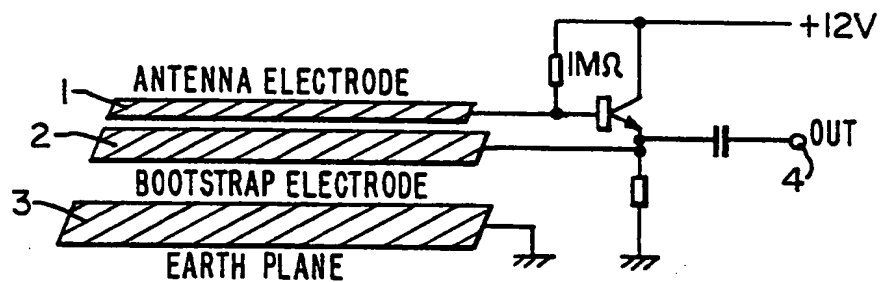
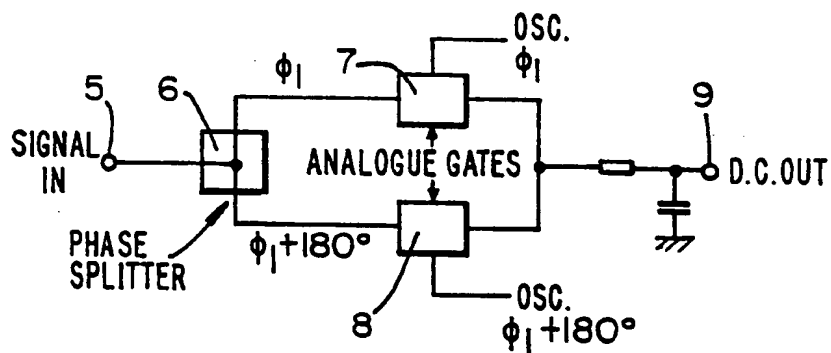
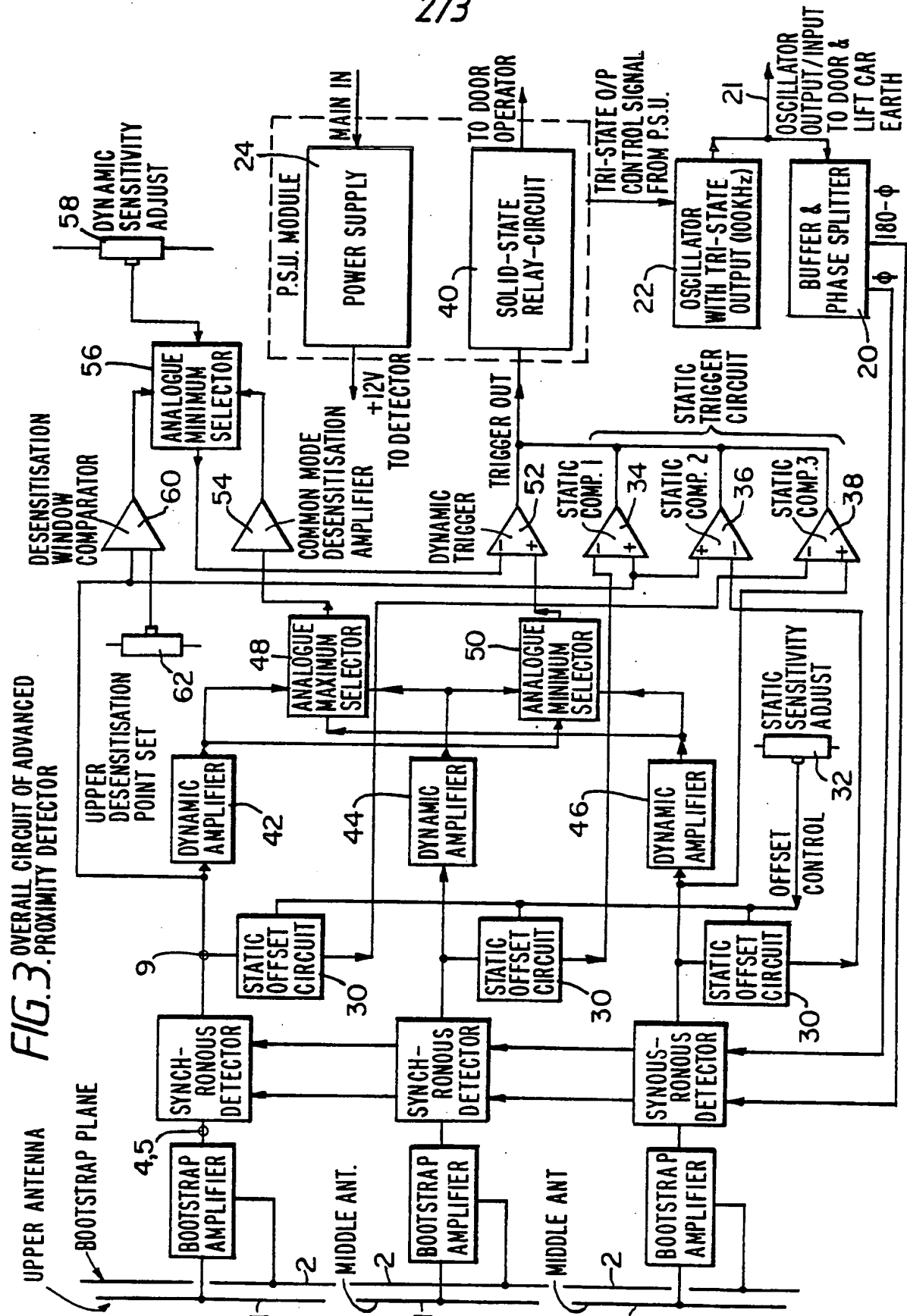


FIG. 2.



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SUBSTITUTE SHEET



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SENSITIVITY IS LOW IF DETECTOR  
ANTENNA IS APPROACHED FROM CAR  
INTERIOR, HIGH IF APPROACHED FROM  
LANDING (FULL SENSITIVITY IS MAIN-  
TAINED FOR OBJECTS BETWEEN DOORS)

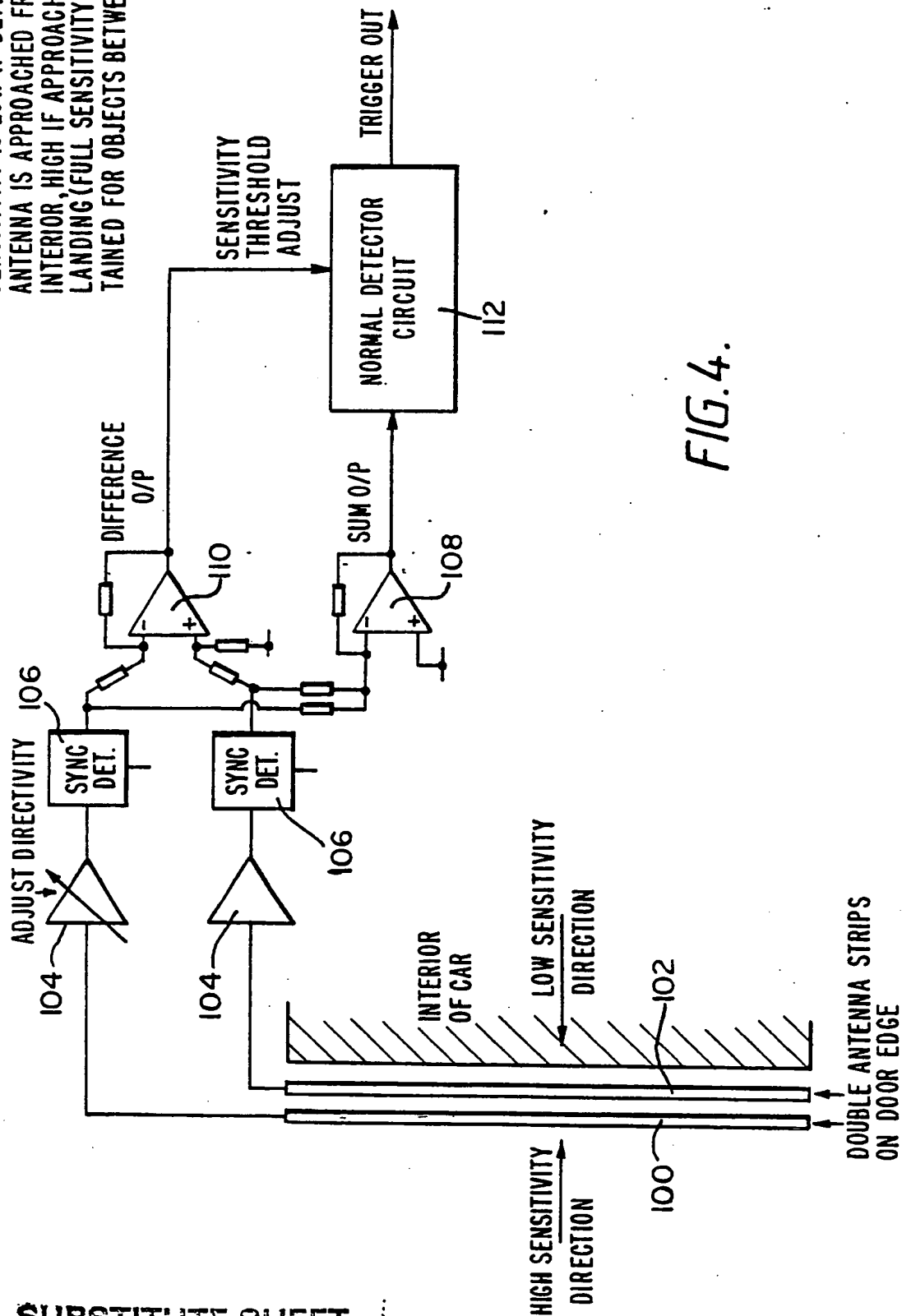


FIG. 4.